No News is Good News: 
An Asymmetric Model of Changing 
Volatility in Stock Returns

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Abstract: It seems plausible that an increase in stock market volatility raises required stock returns, and thus lowers stock prices. We develop a formal model of this volatility feedback effect using a simple model of changing variance (a quadratic generalized autoregressive conditionally heteroskedastic, or QGARCH, model). Our model is asymmetric and helps to explain the negative skewness and excess kurtosis of U.S. monthly and daily stock returns over the period 1926-88. We find that volatility feedback normally has little effect on returns, but it can be important during periods of high volatility.

Keywords: autoregressive conditional heteroskedasticity, crashes, skewness, stock returns, volatility.

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1 Introduction

One striking characteristic of the stock market is that the volatility of returns can be very different at different times. Estimates of the standard deviation of monthly stock returns reported in French, Schwert, and Stambaugh (1987), Schwert (1989), and below range from a low of 2% in the early 1960’s to a high of 20% in the early 1930’s. Daily volatility also fluctuates and can change very rapidly: we estimate that the standard deviation of daily returns increased from about 1% to almost 7% in the few days around the stock market crash of October 1987. These seven- to- tenfold changes in standard deviation correspond to 50- to- 100-fold changes in variance.

It seems plausible that changes in volatility of this magnitude may have important effects on required stock returns and thus on the level of stock prices. This “volatility feedback” effect has been emphasized by Pindyck (1984) and French, Schwert, and Stambaugh (1987). Volatility feedback is an appealing idea because it has the potential to help explain some other facts about stock returns. For example, large negative stock returns are more common than large positive ones, so stock returns are negatively skewed. This skewness, or contemporaneous asymmetry, shows up clearly in the pattern of extreme moves in stock prices in the postwar period. Of the five largest one-day movements in the S&P 500 index since World War II, four are declines in the index and only one is an increase; of the ten largest movements, eight are declines and only two are increases [Cutler, Poterba, and Summers (1989)]. A similar but weaker pattern is visible in the history of daily stock returns over a longer period starting in 1885: six of the ten largest movements in this period are declines and four are increases [Schwert (1990b)].

In addition, extreme stock market movements are more common than would be expected if stock returns were drawn from a normal distribution. This excess kurtosis is not just the result of changing volatility, because it is still present after returns are normalized by their estimated conditional standard deviations [Bollerslev (1987)]. The stock market decline on October 19, 1987 was a large drop even conditional on price movements observed earlier that month.

Finally, volatility is typically higher after the stock market falls than after
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it rises, so stock returns are negatively correlated with future volatility. This
correlation, or predictive asymmetry, was first discussed by Black (1976), who
argued that it could be due to the increase in leverage that occurs when the
market value of a firm declines. However, it seems that the leverage effect is too
small to fully account for this phenomenon [Christie (1982), Schwert (1989)].

In principle, volatility feedback can explain these characteristics of returns even if the underlying shocks to the market are conditionally normally
distributed. Suppose there is a large piece of good news about future dividends.
Large pieces of news tend to be followed by other large pieces of news (volatility
is persistent), so this piece of news increases future expected volatility, which in
turn increases the required rate of return on stock and lowers the stock price,
dampening the positive impact of the dividend news. Now consider a large piece
of bad news about future dividends. Once again, the stock price falls because
higher volatility raises the required rate of return on stock, but now the volatility
effect amplifies the negative impact of the dividend news. Large negative stock
returns are therefore more common than large positive ones, and the amplification
of negative returns can produce excess kurtosis. In contrast, the arrival of
a small piece of news lowers future expected volatility and increases the stock
price. In the extreme case in which no news arrives, the market rises because “no
news is good news” about future volatility. Volatility feedback therefore implies
that stock price movements are correlated with future volatility.

A number of authors have explored these ideas. Brown, Harlow, and
Tinic (1988) show that stock price reactions to unfavorable news events tend
to be larger than reactions to favorable events. They attribute this finding to
volatility feedback. Poterba and Summers (1986), on the other hand, argue that
volatility feedback could not be important because changes in volatility are too
short-lived to have a major effect on stock prices. French, Schwert, and Stam-
baugh (1987) regress stock returns on innovations in volatility and find a nega-
tive coefficient, which they attribute to volatility feedback. Haugen, Talmor,
and Torous (1991) report a similar result. Early research uses moving aver-
age measures of volatility, but recent work [Akgiray (1989), Bollerslev (1987),
Chou (1988), and French, Schwert, and Stambaugh (1987)] uses the “generalized
autoregressive conditionally heteroskedastic” or GARCH model of Engle (1982)
and Bollerslev (1986). GARCH estimates of stock market variance are typically more persistent than moving average estimates, which allows a greater role for volatility feedback. Attanasio and Wadhwani (1989) and Chou (1988) present some Monte Carlo evidence that GARCH estimates of persistence in variance are superior to moving average estimates in finite samples.

Despite the volume of research on the subject, this paper is the first to present a fully worked out formal model of volatility feedback. Earlier papers have at most discussed volatility feedback informally, using it to interpret estimates of GARCH models for stock returns. The basic GARCH model assumes a constant mean stock return, so it does not capture the mechanism underlying volatility feedback. The “GARCH-in-mean” or GARCH-M model [Engle, Lilien, and Robins (1987)] allows the conditional mean stock return to depend on the conditional variance of the return, but when innovations are assumed to be conditionally normal this model still imposes zero correlation between returns and future volatility, as well as zero conditional skewness and zero excess kurtosis. French, Schwert, and Stambaugh (1987) estimate a GARCH-M model with conditionally normal innovations and find a significant positive relation between the conditional mean and variance of stock returns. They argue that it would be desirable to take account of negative skewness from volatility feedback (pp. 22–23), but they do not try to do this. Chou (1988) also combines an informal discussion of the negative effect of volatility on prices with a formal GARCH-M model that does not accommodate this effect.

There are some second-generation GARCH models that allow returns to be correlated with future volatility, notably the “exponential GARCH” or EGARCH model of Nelson (1991) and the “quadratic GARCH” or QGARCH model of Engle (1990) and Sentana (1991), as well as the Markov switching model of Turner, Startz, and Nelson (1989). We take the QGARCH model as our starting point, since it is analytically tractable and captures the phenomenon of predictive asymmetry without appealing to volatility feedback, which seems desirable since the leverage effect is a plausible explanation for at least some of the predictive asymmetry observed in the data. The basic QGARCH model has conditionally normal innovations, however, so it does not fit the negative skewness or excess kurtosis of returns. We therefore build a model of volatility feedback that amplifies the
predictive asymmetry of the basic \textit{QGARCH} model and creates negative skewness and excess kurtosis in returns. Our work is distinguished from statistical models with nonnormal return innovations [Engle and González-Rivera (1989), Nelson (1991)] by the fact that the nonnormality in our model comes exclusively from volatility feedback and is pinned down by the model parameters describing first and second moments: no new parameters are introduced to fit the third and fourth moments of returns.

Much of the work we have described applies a statistical model directly to stock returns. Of course, an economic explanation of the behavior of stock returns requires that a statistical model be applied to exogenous variables, with the behavior of stock returns emerging from the solution of an economic model. Our paper takes a step in this direction. We do not work with a full general equilibrium model of the economy, but rely on two simple assumptions. First, we assume that news about stock dividends follows a \textit{QGARCH} model. Second, we assume that the expected return on a stock is a linear function of the conditional variance of the news about dividends. (As we explain further below, this assumption can be weakened: we can allow for other sources of variation in expected returns, which appear to be important in practice, provided that a \textit{QGARCH} process adequately characterizes the innovations in stock prices caused by dividend news and by non-volatility-induced changes in expected returns.) We combine these two assumptions with the log-linear approximate asset pricing framework of Campbell and Shiller (1988) and Campbell (1991) to get an implied process for stock returns.

Table 1 illustrates the nonnormality of U.S. stock return data. The table reports skewness and excess kurtosis for raw stock returns and for the normalized residuals of a \textit{QGARCH-M} model. Stock returns are log excess returns on the Center for Research in Securities Prices (CRSP) value-weighted index of New York Stock Exchange and American Stock Exchange stocks over a one-month Treasury bill, measured at monthly and daily intervals over the period 1926–88 as well as over the subperiods 1926–51 and 1952–88. The table clearly shows that neither log excess returns nor residuals from a \textit{QGARCH-M} model are normal or symmetric. In particular, there is evidence that log excess returns are negatively skewed and leptokurtic.
Excess returns (ER) are log excess returns on the value-weighted CRSP index over a one-month Treasury bill return. QGARCH-M residuals are the residuals from the QGARCH(1,1)-M and QGARCH(1,2)-M models estimated in tables 2a and 2b, divided by their estimated standard deviation. If the QGARCH models are correctly specified, these residuals should have a standard normal distribution. Mean and variance have been multiplied by 1000 for excess returns. Standard errors are computed under the null hypothesis that returns or residuals are normally distributed.

The QGARCH(1,1)-M model for monthly excess returns is obtained by setting $\lambda = 0$ in eq. (12) in the text.

\begin{equation}
\begin{align*}
h_{t+1} &= \mu + \gamma \sigma_t^2 + \eta_{d,t+1} \\
\sigma_t^2 &= \omega + \alpha (\eta_{d,t} - b)^2 + \beta \sigma_{t-1}^2 + \gamma \sigma_{t-1}^2,
\end{align*}
\end{equation}

where $h_{t+1}$ is the monthly log excess return and $\sigma_t^2$ is the conditional variance of $h_{t+1}$.

The QGARCH(1,2)-M model for daily excess returns is given by the QGARCH(1,2) analogues of the above equations.

\begin{equation}
\begin{align*}
h_{t+1} &= \mu + \gamma \sigma_t^2 + \eta_{d,t+1} \\
\sigma_t^2 &= \omega + \alpha_1 (\eta_{d,t} - b)^2 + \alpha_2 (\eta_{d,t-1} - b)^2 + \beta \sigma_{t-1}^2 + \gamma \sigma_{t-1}^2,
\end{align*}
\end{equation}

where $h_{t+1}$ is the daily log excess return and $\sigma_t^2$ is the conditional variance of $h_{t+1}$.

### Table 1

<table>
<thead>
<tr>
<th>Data Set</th>
<th>Mean</th>
<th>Variance</th>
<th>Skewness</th>
<th>Excess Kurtosis</th>
</tr>
</thead>
<tbody>
<tr>
<td>Monthly CRSP ER</td>
<td>4.797</td>
<td>3.240</td>
<td>-0.443</td>
<td>6.877</td>
</tr>
<tr>
<td>1/26–12/88</td>
<td>(2.070)</td>
<td>(0.167)</td>
<td>(0.089)</td>
<td>(0.178)</td>
</tr>
<tr>
<td>Monthly QGARCH-M</td>
<td>-0.016</td>
<td>1.014</td>
<td>-0.865</td>
<td>2.936</td>
</tr>
<tr>
<td>1/26–12/88</td>
<td>(0.037)</td>
<td>(0.052)</td>
<td>(0.089)</td>
<td>(0.178)</td>
</tr>
<tr>
<td>Monthly CRSP ER</td>
<td>5.213</td>
<td>5.306</td>
<td>-0.342</td>
<td>4.933</td>
</tr>
<tr>
<td>1/26–12/51</td>
<td>(4.124)</td>
<td>(0.425)</td>
<td>(0.139)</td>
<td>(0.277)</td>
</tr>
<tr>
<td>Monthly QGARCH-M</td>
<td>-0.039</td>
<td>1.039</td>
<td>-0.903</td>
<td>2.379</td>
</tr>
<tr>
<td>1/26–12/51</td>
<td>(0.058)</td>
<td>(0.083)</td>
<td>(0.139)</td>
<td>(0.277)</td>
</tr>
<tr>
<td>Monthly CRSP ER</td>
<td>4.505</td>
<td>1.796</td>
<td>-0.648</td>
<td>3.086</td>
</tr>
<tr>
<td>1/52–12/88</td>
<td>(2.011)</td>
<td>(0.121)</td>
<td>(0.116)</td>
<td>(0.232)</td>
</tr>
<tr>
<td>Monthly QGARCH-M</td>
<td>0.002</td>
<td>1.003</td>
<td>-0.498</td>
<td>1.354</td>
</tr>
<tr>
<td>1/52–12/88</td>
<td>(0.048)</td>
<td>(0.067)</td>
<td>(0.116)</td>
<td>(0.232)</td>
</tr>
<tr>
<td>Daily CRSP ER</td>
<td>0.215</td>
<td>0.128</td>
<td>-0.344</td>
<td>19.926</td>
</tr>
<tr>
<td>1/26–12/30/88</td>
<td>(0.087)</td>
<td>(0.001)</td>
<td>(0.019)</td>
<td>(0.038)</td>
</tr>
<tr>
<td>Daily QGARCH-M</td>
<td>-0.010</td>
<td>1.005</td>
<td>-0.516</td>
<td>4.398</td>
</tr>
<tr>
<td>1/26–12/30/88</td>
<td>(0.008)</td>
<td>(0.011)</td>
<td>(0.019)</td>
<td>(0.038)</td>
</tr>
<tr>
<td>Daily CRSP ER</td>
<td>0.213</td>
<td>0.204</td>
<td>0.016</td>
<td>10.909</td>
</tr>
<tr>
<td>1/26–12/31/51</td>
<td>(0.163)</td>
<td>(0.003)</td>
<td>(0.028)</td>
<td>(0.056)</td>
</tr>
<tr>
<td>Daily QGARCH-M</td>
<td>-0.013</td>
<td>1.006</td>
<td>-0.442</td>
<td>2.824</td>
</tr>
<tr>
<td>1/26–12/31/51</td>
<td>(0.011)</td>
<td>(0.016)</td>
<td>(0.028)</td>
<td>(0.056)</td>
</tr>
<tr>
<td>Daily CRSP ER</td>
<td>0.216</td>
<td>0.066</td>
<td>-1.782</td>
<td>45.515</td>
</tr>
<tr>
<td>1/25–12/30/88</td>
<td>(0.084)</td>
<td>(0.001)</td>
<td>(0.025)</td>
<td>(0.051)</td>
</tr>
<tr>
<td>Daily QGARCH-M</td>
<td>-0.011</td>
<td>1.010</td>
<td>-0.467</td>
<td>5.079</td>
</tr>
<tr>
<td>1/25–12/30/88</td>
<td>(0.010)</td>
<td>(0.015)</td>
<td>(0.025)</td>
<td>(0.051)</td>
</tr>
</tbody>
</table>
The circles plot the sample skewness of $qgarch(1,1)$-m residuals, $\hat{\eta}_{d,t+1}$, normalized by their conditional standard deviations, $\hat{\sigma}_t$. The residuals are taken from the model estimated in table 2a, top panel, row 1, using monthly log excess returns on the value-weighted CRSP index over a one-month Treasury bill return. Skewness is computed in each of the seven calendar decades during the period January 1926–December 1988. The error bars give the 95% confidence intervals. The $qgarch(1,1)$-m model for monthly excess returns is obtained by setting $\lambda = 0$ in eqs. (6) and (12') in the text:

$$h_{t+1} = \mu + \gamma \sigma_t^2 + \eta_{d,t+1}$$
$$\sigma_t^2 = \omega + \alpha (\eta_{d,t} - b)^2 + \beta \sigma_{t-1}^2,$$

where $h_{t+1}$ is the monthly log excess return and $\sigma_t^2$ is the conditional variance of $h_{t+1}$.

The dashed line plots the sample skewness of $qgarch(1,2)$-m residuals, $\hat{\eta}_{d,t+1}$, normalized by their conditional standard deviations, $\hat{\sigma}_t$. The residuals are taken from the model estimated in table 2b, top panel, row 1, using daily log excess returns on the value-weighted CRSP index over a one-month Treasury bill return. Skewness is computed in each of the sixty-three calendar years during the period January 2, 1926–December 30, 1988. The $qgarch(1,2)$-m model for daily excess returns is obtained by setting $\lambda = 0$ in the $qgarch(1,2)$ analogues of eqs. (6) and (12') in the text:

$$h_{t+1} = \mu + \gamma \sigma_t^2 + \eta_{d,t+1}$$
$$\sigma_t^2 = \omega + \alpha_1 (\eta_{d,t} - b)^2 + \alpha_2 (\eta_{d,t-1} - b)^2 + \beta \sigma_{t-1}^2,$$

where $h_{t+1}$ is the daily log excess return and $\sigma_t^2$ is the conditional variance of $h_{t+1}$.

The strong evidence for negative skewness reported here does not depend on our use of a QGARCH-M model rather than a GARCH-M or a simple GARCH model. [GARCH-M models were estimated in the first version of this paper, Campbell and...
Hentschel (1991), and the residuals were, if anything, slightly more skewed.] The evidence for skewness does, however, depend on our using log returns rather than simple returns. The log return is the appropriate concept, since the standard geometric Brownian motion model of stock prices implies that the log return, not the simple return measured in discrete time, is normally distributed. The evidence for negative skewness is robust to sample period, as we show in fig. 1 by plotting the sample skewness of standardized QGARCH-M residuals over shorter subsamples. The standardized residuals for monthly log excess returns are negatively skewed in each of the decades of our sample. Although the evidence for daily data is weaker, there is still negative skewness in the great majority of years.

In the next section, we explain our model of volatility feedback. In section 3, we apply our model to U.S. stock market data. Section 4 summarizes our conclusions and discusses some interesting directions for further research.

2 An Asymmetric Model of Changing Volatility

2.1 The Campbell-Shiller Framework

If we are to model the effect of changing volatility on stock prices, we need a framework that allows prices to be affected by changing expectations about both dividends and required returns. The difficulty is that the standard present value relation is nonlinear when expected returns vary through time making it intractable except in a few special cases.

Campbell and Shiller (1988) propose a log-linear approximation to the standard model. They argue that the approximation is both tractable and surprisingly accurate. Campbell and Shiller originally derived their approximation for a beginning-of-period (cum dividend) stock price, but we follow Campbell (1991) and work with an end-of-period price, which is more standard in the finance literature. We define the one-period natural log real holding return on a stock as $h_{t+1} = \log(P_{t+1} + D_{t+1}) - \log(P_t)$, where $P_t$ is the real stock price measured at the end of period $t$ (ex dividend), and $D_t$ is the real dividend paid during period $t$. The right hand side of this identity is a nonlinear function of the log stock
price and the log dividend; it can be approximated, using a first-order Taylor expansion, as

\[ h_{t+1} \approx k + \rho p_{t+1} + (1 - \rho)d_{t+1} - p_t, \]  

(1)

where lower-case letters are used for logs. The parameter \( \rho \) is the average ratio of the stock price to the sum of the stock price and the dividend, a number slightly smaller than one, and the constant \( k \) is a nonlinear function of \( \rho \). Eq. (1) replaces the log of the sum of price and dividend with a weighted average of log price and log dividend. Intuitively, the future log stock price gets a much larger weight than the future log dividend because a given percentage change is absolutely larger when it occurs in the stock price than when it occurs in the dividend.

Eq. (1) can be thought of as a difference equation relating \( p_t \) to \( p_{t+1} \), \( d_{t+1} \), and \( h_{t+1} \). It holds ex post, but it also holds ex ante as an expectational difference equation. Campbell and Shiller impose the terminal condition that \( \lim_{i \to \infty} E_t \rho^i p_{t+i} = 0 \). This condition rules out “rational bubbles” which would cause explosive behavior of the log stock price. With this terminal condition, the ex ante version of (1) can be solved forward to obtain

\[ p_t = \frac{k}{1 - \rho} + (1 - \rho) E_t \sum_{j=0}^{\infty} \rho^j d_{t+1+j} - E_t \sum_{j=0}^{\infty} \rho^j h_{t+1+j}. \]  

(2)

This equation is useful because it enables one to calculate the effect on the stock price of a change in expected stock returns. It says that the log stock price \( p_t \) can be written as an expected discounted value of all future dividends \( d_{t+1+j} \) less future returns \( h_{t+1+j} \), discounted at the constant rate \( \rho \) plus a constant \( k/(1 - \rho) \).

If the stock price is high today, this must mean that future expected dividends are high unless returns are expected to be low in the future. Note that eq. (2) is not an economic model, but has been derived by approximating an identity and imposing a terminal condition. It is best thought of as a consistency condition that must be satisfied by any reasonable set of expectations.

Campbell (1991) uses eq. (2) to substitute \( p_t \) and \( p_{t+1} \) out of (1). This gives another useful expression:

\[ h_{t+1} - E_t h_{t+1} = (E_{t+1} - E_t) \sum_{j=0}^{\infty} \rho^j \Delta d_{t+1+j} - (E_{t+1} - E_t) \sum_{j=1}^{\infty} \rho^j h_{t+1+j}, \]  

(3)
Sec. 2]

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or in more compact notation,

\[ v_{h,t+1} = \eta_{d,t+1} - \eta_{h,t+1}, \quad (4) \]

where \( v_{h,t+1} \) denotes the unexpected stock return at time \( t + 1 \), and \( \eta_{d,t+1} \) and \( \eta_{h,t+1} \) denote news about dividends and future returns respectively. Once again, this equation should be thought of as a consistency condition for expectations. If the unexpected stock return is negative, then either expected future dividend growth must be lower, or expected future stock returns must be higher, or both. There is no behavioral model behind eq. (4); it is simply an approximation to an identity.

We work below with excess log stock returns, measured relative to a short-term interest rate. Campbell (1991) shows that the decomposition (4) is equally valid for excess stock returns, provided that \( \eta_{d,t+1} \) is reinterpreted to include news about real interest rates as well as news about real dividends. In this paper we use the notation of eq. (4) and refer to \( \eta_{d,t+1} \) as “news about dividends”. In our empirical work, however, we do not directly measure \( \eta_{d,t+1} \). It is a residual term that may contain real interest rate shocks as well as other shocks that we do not explicitly model. In practice, we believe that changes in expected excess stock returns, arising from some other source than changing volatility, are an important component of the shock we write as \( \eta_{d,t+1} \). The shock we write as \( \eta_{h,t+1} \) should be thought of as capturing the volatility feedback effect, but not necessarily all changes in expected excess stock returns. We discuss this point further in section 4 below.

2.2 News About Dividends and News About Volatility

The first determinant of the stock return in eq. (4) is the news about future dividends, \( \eta_{d,t+1} \). We treat this as an exogenous shock which follows a conditionally normal QGARCH process [Engle (1990), Sentana (1991)]. For simplicity we describe the QGARCH(1,1) case and generalize to the QGARCH \((p,q)\) case in appendix A. The QGARCH(1,1) model is

\[ \eta_{d,t+1} \sim N(0, \sigma^2_t), \quad (5) \]
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\[ \sigma_t^2 = \omega + \alpha (\eta_{d,t} - b)^2 + \beta \sigma_{t-1}^2. \]  

\( (6) \)

In order to ensure that the conditional variance is always positive, the parameters \( \omega, \alpha, \) and \( \beta \) must all be positive. The parameter \( \alpha \) measures the extent to which a squared return today feeds through into future volatility, while the sum \( \alpha + \beta \) measures the persistence of volatility. The unconditional variance of the process is \( (\omega + \alpha b^2)/(1 - (\alpha + \beta)) \).

The QGARCH model introduces a parameter \( b \) that is absent from the simple GARCH model; when \( b = 0 \), the QGARCH model reduces to the GARCH model. Our prior expectation is that \( b \) is positive, although this is by no means required. A positive \( b \) creates a negative correlation between the dividend news, \( \eta_{d,t} \), and the conditional volatility of next period’s dividend news, \( \sigma_t^2 \), because a negative return will increase volatility more than a positive return of the same size. Thus the QGARCH model captures the phenomenon of predictive asymmetry.

The other determinant of the stock return in eq. (4) is the news about future expected returns. We assume that the conditional expected return \( E_t h_{t+1} \) is determined by the volatility of the news variable \( \eta_{d,t+1} \):

\[ E_t h_{t+1} = \mu + \gamma E_t \eta_{d,t+1}^2 = \mu + \gamma \sigma_t^2. \]  

\( (7) \)

As we shall see, this is not quite equivalent to the conventional assumption that the expected return is linear in the volatility of the return itself, but our empirical estimates imply that the discrepancy is small.

Following Merton (1980), the coefficient \( \gamma \) in eq. (7) is usually interpreted as the coefficient of relative risk aversion. Even ignoring the difference between the stock return and the news variable \( \eta_{d,t+1} \), eq. (7) can be derived in general equilibrium only under restrictive assumptions. In a model that distinguishes the coefficient of relative risk aversion from the elasticity of intertemporal substitution, Campbell (1992) shows that eq. (7) holds for the market portfolio, with \( \gamma \) equal to relative risk aversion, if the elasticity of intertemporal substitution is one. Campbell also discusses other circumstances under which eq. (7) holds as an approximation.

Eq. (7) and the QGARCH(1,1) process (6) imply that the expected return
at any date in the future can be written as

\[ E_t h_{t+1+j} = \mu + \gamma \frac{\omega + \alpha b^2}{1 - (\alpha + \beta)} + \gamma (\alpha + \beta)^3 \left( \sigma^2_t - \frac{\omega + \alpha b^2}{1 - (\alpha + \beta)} \right). \] (8)

The second term on the right hand side of eq. (8) is \( \gamma \) times the unconditional variance of the news process. The third term is \( \gamma \) times the deviation of today’s conditional variance from the unconditional variance, discounted using the persistence of volatility \( \alpha + \beta \). Eq. (8) implies that the discounted sum of all future expected returns is

\[ E_t \sum_{j=0}^{\infty} \rho^j h_{t+1+j} = \frac{\mu}{1 - \rho} \]

\[ + \frac{\gamma}{1 - \rho} \left( \omega + \alpha b^2 \right) + \frac{\gamma}{1 - \rho(\alpha + \beta)} \left( \sigma^2_t - \frac{\omega + \alpha b^2}{1 - (\alpha + \beta)} \right). \] (9)

This discounted sum of expected returns helps determine the level of the stock price in eq. (2). The second and third terms on the right hand side of eq. (9) can be interpreted as the “volatility discount” on the stock price, or the extent to which the price is lower than it would be if there were no uncertainty about future dividends. The second term is the unconditional mean volatility discount, while the third term represents the variation in the discount caused by the changing conditional volatility of news about dividends.

These equations describe the levels of expected returns. It is also straightforward to calculate the revision from time \( t \) to time \( t + 1 \) in the discounted value of future returns. This is

\[ \eta_{h,t+1} = (E_{t+1} - E_t) \sum_{j=1}^{\infty} \rho^j h_{t+1+j} = \lambda \left( \eta^2_{d,t+1} - \sigma_t^2 - 2b \eta d_{t+1} \right), \] (10)

where \( \lambda \) is related to the other parameters of the model by

\[ \lambda = \frac{\gamma \rho \alpha}{1 - \rho(\alpha + \beta)}. \] (11)

At time \( t + 1 \), the innovation to volatility is the difference between the squared innovation \( \eta^2_{d,t+1} \) and its conditional expectation \( \sigma^2_t \), minus 2\( b \) times the difference between the return \( \eta d_{t+1} \) and its conditional expectation of zero. This last
linear term appears in the QGARCH model but not in the simpler GARCH model which sets $b = 0$. To obtain the revision in the discounted value of future stock returns, one multiplies the volatility innovation by the parameter $\lambda$; $\lambda$ in turn depends on the effect of volatility on the expected stock return, $\gamma$, the effect of an innovation on next period’s volatility, $\alpha$, and the persistence of volatility, $\alpha + \beta$. Since $\rho$ is less than unity, $\lambda$ is well defined even if volatility has infinite persistence and follows an integrated GARCH model with $\alpha + \beta = 1$.

Eqs. (4), (7), (10), and (11) can now be combined to write the stock return as

$$h_{t+1} = \mu + \gamma \sigma_t^2 + \eta_{d,t+1} - \lambda \left( \eta_{d,t+1}^2 - \sigma_t^2 - 2b \eta_{d,t+1} \right)$$

(12)

$$= \mu + \gamma \sigma_t^2 + \kappa \eta_{d,t+1} - \lambda \left( \eta_{d,t+1}^2 - \sigma_t^2 \right),$$

(12')

where $\kappa = 1 + 2\lambda b$. The first three terms in eq. (12) comprise the standard GARCH-M model that has previously been used to describe stock returns. The final term, which is new, says that an unusually large realization of dividend news, of either sign, will increase volatility, lower the stock price, and cause a negative unexpected stock return; moreover, a positive piece of dividend news will tend to reduce volatility and increase the stock return (when $b$ is positive).

The strength of this volatility feedback effect is measured by the parameter $\lambda$. Eq. (12') rewrites eq. (12) to show that the stock return is a quadratic function of the underlying news with linear coefficient $\kappa$ and quadratic coefficient $\lambda$. $\kappa$ is greater than one when the QGARCH parameter $b$ is positive, but it is always very close to one for the parameter values estimated below.

Our analysis so far has assumed a QGARCH(1, 1) process for volatility. However, we show in appendix A that eq. (12') holds for any QGARCH($p, q$) process provided that the parameters $\kappa$ and $\lambda$ are appropriately redefined in terms of the underlying parameters governing the evolution of variance. In the QGARCH(1, 2) model which we use for daily data, for example, the variance process is $\sigma_t^2 = \alpha_1 (\eta_{d,t} - b)^2 + \alpha_2 (\eta_{d,t-1} - b)^2 + \beta \sigma_{t-1}^2$. The coefficient $\lambda$ has the form given in eq. (11) except that $\alpha$ is replaced by $\alpha_1 + \rho \alpha_2$, while $\kappa$ remains unchanged in terms of $b$ and $\lambda$. Thus eq. (12') is quite general and we can proceed
Figure 2: Unexpected returns and news.
The straight dashed line is a 45° line which gives the relation between unexpected returns and news when \( \lambda = 0 \). The solid curve gives the relation between unexpected returns and news when \( \lambda = 2.398 \), the value estimated over the second subsample in table 2b, bottom panel, row 2. The relation plotted is given by the last two terms on the right hand side of eq. (12) in the text:

\[
\kappa \eta_{d,t+1} + 1 - \lambda (\eta_{d,t+1}^2 - \sigma_t^2),
\]

where \( \eta_{d,t+1} \) is the news at time \( t+1 \).

The conditional standard deviation \( \sigma_t = 0.05 \), and the horizontal range of the figure is three conditional standard deviations on either side of zero.

To discuss its implications for the behavior of stock returns.

2.3 Characteristics of the Returns Process

To understand eq. (12), it is helpful to plot the relationship between the cash flow news \( \eta_{d,t+1} \) and the unexpected stock return \( v_{h,t+1} = \kappa \eta_{d,t+1} - \lambda (\eta_{d,t+1}^2 - \sigma_t^2) \).

Fig. 2 plots the stock return against the news for parameter values that we estimate below (in table 2b) using postwar daily U.S. data. The coefficient \( \lambda \) is 2.398, while \( \kappa \) is 1.012. The figure assumes that the conditional standard deviation \( \sigma_t \) is 0.05 (close to the postwar maximum reached during October 1987).

The horizontal range of fig. 2 is three standard deviations on either side of zero, so that news events lying outside the range of the figures are exceedingly unlikely.

Since \( \kappa \) is so close to one, the unexpected stock return is almost exactly the news less \( \lambda (\eta_{d,t+1}^2 - \sigma_t^2) \). Thus the unexpected stock return (the solid curve) lies
above the 45° line in the middle of the figure, where the absolute value of the news is less than its conditional standard deviation. This is the “no news is good news” effect. If there is no dividend news at all, the stock market rises because the absence of dividend news implies that volatility and required returns will tend to be lower in the future. Conversely, the unexpected return lies below the 45° line at the left and the right of the figure, where the dividend news is large in absolute value. Large declines in stock prices are amplified, while large increases are dampened. In fact, the model implies that the maximum possible return is $\mu + (\gamma + \lambda)\sigma_t^2 + \kappa^2 / (4\lambda)$, which is achieved when $\eta_{d,t+1} = \kappa / (2\lambda) = b+1/(2\lambda)$. Any larger piece of good dividend news actually gives a lower stock return because the indirect volatility effect outweighs the direct dividend effect. Whether this behavior is relevant for observed stock returns depends on the parameters $b$ and $\lambda$ and the range of $\sigma_t^2$. In our empirical work we assume that all observed returns are generated by underlying shocks $\eta_{d,t+1}$ less than $b+1/(2\lambda)$. We obtain moderate estimates of $\lambda$, for which this assumption is not restrictive.

The degree of curvature in the relation between news and returns depends on the level of $\sigma_t^2$. If $\sigma_t^2$ is small, then $\eta_{d,t+1}^2$ is almost always small and the quadratic term has little weight relative to the linear term in eq. (12). Thus for low levels of volatility the solid line in fig. 2 is closer to the 45° diagonal and exhibits less curvature over the relevant range. On the other hand, if $\sigma_t^2$ is large, the quadratic term becomes much more important. To understand this point more generally, observe that eq. (12) can be rewritten as

$$\frac{\eta_{h,t+1}}{\sigma_t} = (\kappa + \lambda \sigma_t) \left[ \frac{\kappa}{\kappa + \lambda \sigma_t} \left\{ \frac{\eta_{d,t+1}}{\sigma_t} \right\} + \frac{\lambda \sigma_t}{\kappa + \lambda \sigma_t} \left\{ 1 - \left( \frac{\eta_{d,t+1}}{\sigma_t} \right)^2 \right\} \right].$$

(13)

The variable $\eta_{d,t+1}/\sigma_t$ has a standard normal distribution. The distribution of unexpected returns, normalized by $\sigma_t$, is thus a mixture of a normal distribution and a demeaned, negative $\chi^2(1)$. The normal distribution has relative weight $\kappa / (\kappa + \lambda \sigma_t)$, while the negative $\chi^2(1)$ has relative weight $\lambda \sigma_t / (\kappa + \lambda \sigma_t)$). In times of low volatility, returns is very close to normal, but in periods of high volatility returns take on some of the characteristics of a negative $\chi^2(1)$ distribution.

This shifting distribution of returns is the result of an important property of both the GARCH and QGARCH models: the volatility of variance increases very
An Asymmetric Model of Changing Volatility

Figure 3:

The conditional standard deviation of dividend news, 1926–88.
The solid line plots the monthly average of the conditional standard deviation of daily news implied by the restricted model estimated over the full sample (table 2b, top panel, row 2). The dashed line is the monthly average conditional standard deviation implied by the restricted model estimated over subsamples (Table 2b, bottom two panels, row 2). The model for daily excess returns is given by the \texttt{qgarch}(1,2) analogues of eqs. 6), (11), and (12′) in the text:

\[
\begin{align*}
  h_{t+1} &= \mu + \gamma \sigma_t^2 + \kappa \eta_{d,t+1} - \lambda (\sigma_{d,t+1}^2 - \sigma_t^2) \\
  \sigma_t^2 &= \omega + \alpha_1 (\eta_{d,t} - b)^2 + \alpha_2 (\eta_{d,t-1} - b)^2 + \beta \sigma_{t-1}^2 \\
  \lambda &= \frac{\gamma \rho (\alpha_1 + \rho \alpha_2)}{1 - \rho (\alpha_1 + \rho \alpha_2 + \beta)} \\
  \kappa &= 1 + 2 \lambda b,
\end{align*}
\]

where \( h_{t+1} \) is the daily log excess return and \( \sigma_t^2 \) is the conditional variance of \( h_{t+1} \).

rapidly with the level of variance. To see this for the \texttt{GARCH}(1,1) case, lead eq. (6) by one period and set \( b = 0 \) to obtain

\[
\sigma_{t+1}^2 = \omega + \alpha \sigma_t^2 \left\{ \left( \frac{\eta_{d,t+1}}{\sigma_t} \right)^2 - 1 \right\} + (\alpha + \beta) \sigma_t^2. \tag{14}
\]

The innovations to \( \sigma_{t+1}^2 \) are the product of \( \alpha \sigma_t^2 \) and a demeaned \( \chi^2(1) \) random variable. The conditional variance of \( \sigma_{t+1}^2 \) is therefore proportional to \( \sigma_t^4 \). This feature of the \texttt{GARCH} model enables it to generate long periods of calm with occasional episodes of high and rapidly changing volatility, as seen in fig. 3. It also means that volatility feedback distorts the distribution of returns away from the
normal more strongly when volatility is high than when it is low. As volatility increases, the variance of news about dividends increases with $\sigma^2_t$, but the variance of news about variance, which creates the nonnormality of returns, increases with $\sigma^4_t$. What is important here is not that the variance of GARCH variance increases with its level—this is characteristic of many stochastic processes which are constrained to be positive—but that the variance of GARCH variance increases more than proportionally with its level. This feature of GARCH processes extends to the QGARCH model, in which the nonzero $b$ merely introduces an additional lower order term.

Further insight can be gained by deriving the conditional moments of the returns process. The conditional mean return has already been given in eq. (7). The conditional variance of the return changes through time in the manner of the underlying GARCH process for dividend news. The return variance is in fact slightly higher and more variable than the news variance:

$$\text{Var}_t(h_{t+1}) = \kappa^2 \sigma_t^2 + 2\lambda^2 \sigma_t^4.$$  \hfill (15)

For small $\sigma_t^2$ the second, higher order term is small relative to the underlying news variance and the conditional variance of excess returns is approximately proportional to the conditional variance of dividend news.\footnote{It is also possible to derive the unconditional variance of stock returns, but unlike the conditional moments, this is specific to the particular GARCH model used. The main appeal of the calculation is that it enables us to measure the contribution of volatility feedback to the unconditional variance of returns.}

The returns process is negatively skewed, and the skewness increases with the conditional variance. The expression for skewness is complicated by the fact that the conditional variance of returns does not equal $\sigma_t^2$. It is

$$\text{Skew}_t(h_{t+1}) = -2\lambda \sigma_t \frac{3\kappa^2 + 4\lambda^2 \sigma_t^2}{(\kappa^2 + 2\lambda^2 \sigma_t^4)^{3/2}},$$  \hfill (16)

which increases in absolute value with $\lambda \sigma_t$, approaching a limit of $-2\sqrt{2}$ which is the skewness of a negative $\chi^2(1)$ distribution.

The conditional distribution of stock returns has fat tails even though the GARCH process for dividend news is conditionally normal. The conditional excess
kurtosis of returns is

$$\text{EK}_t(h_{t+1}) = 48\lambda^2\sigma_t^2 \frac{\kappa^2 + \lambda^2\sigma_t^2}{(\kappa^2 + 2\lambda^2\sigma_t^2)^2},$$

(17)

which again increases with $\lambda\sigma_t$, approaching a limit of 12 which is the excess kurtosis of a $\chi^2(1)$ distribution.

Comparing eqs. (15), (16), and (17), it is noteworthy that for small $\lambda$ the conditional excess variance and kurtosis of returns approach zero at a rate proportional to $\lambda^2$. The skewness of returns approaches zero at a rate proportional to $\lambda$, however, so in this sense our model generates “first-order” skewness but only “second-order” excess variance and kurtosis.

These calculations show that our model can explain the contemporaneous asymmetry and excess kurtosis of stock returns. The model also generates a form of predictive asymmetry. The correlation between today’s return and tomorrow’s volatility is

$$\text{Corr}_t(h_{t+1}, \sigma_{t+1}^2) = -\frac{\sqrt{2}(\kappa b + \lambda\sigma_t^2)}{\sqrt{2}(\kappa b + \lambda\sigma_t^2)^2 + (\kappa - 2\lambda b)^2\sigma_t^2}.$$

(18)

There are two sources of correlation between returns and future volatility. The first is the QGARCH effect: even when $\lambda = 0$, the correlation between returns and future volatility equals $-\sqrt{2}(b)/\sqrt{\sigma_t^2 + 2b^2}$. When $b$ is nonzero, this correlation approaches zero as volatility $\sigma_t^2$ increases but approaches $\pm 1$ as volatility declines.

The reason for this behavior is that the QGARCH model achieves asymmetry by a horizontal shift in the parabola relating news to future volatility. Any given shift produces more asymmetry when shocks are tightly clustered around zero than when shocks are widely dispersed. The second source of correlation between returns and future volatility is the volatility feedback effect: even when $b = 0$, the correlation in eq. (18) is $-\sqrt{2}(\lambda\sigma_t)/\sqrt{1 + 2\lambda^2\sigma_t^2}$. When $\lambda$ is positive this correlation approaches $-1$ as volatility increases but approaches zero as volatility declines.

The reason for this behavior is the characteristic of GARCH and QGARCH models discussed above that news about variance becomes more important relative to underlying news as the level of variance increases.

We note also that a stronger form of predictive asymmetry does not hold in our model. It is not true that for any squared return $h_{t+1}^2$, future volatility
is higher if the return is positive than if it is negative. To see this, consider fig. 2. To get a zero unexpected return, the underlying news must be slightly negative. This means that for small squared returns, positive returns correspond to larger declines in volatility. On the other hand, the curvature of the news-return relation means that relatively larger underlying pieces of news are required for large positive returns than for large negative returns. Since large pieces of news raise volatility, positive returns correspond to greater increases in volatility when the squared return is large.

3 Application to U.S. Stock Market Data

3.1 Data and Estimation Method

In this section we apply our model to monthly and daily data on excess stock returns over the period 1926–88. The monthly excess return series is the log return on the value-weighted CRSP index, less the log return on a one-month Treasury bill as reported by Ibbotson Associates (1989). The daily return series is the log value-weighted CRSP index return from July 3, 1962, spliced to Schwert’s (1990a) daily index return for the earlier part of the sample period. These daily returns include dividends. To form a daily excess return we subtract $1/N_j$ times the log return on the Ibbotson one-month Treasury bill rate, where $N_j$ is the number of trading days in month $j$.

We report results for the full 1926–88 sample period as well as for the sub-samples before and after the end of 1951. The 1951 break point corresponds to a change in interest rate regime with the Fed-Treasury Accord, and it separates the Great Depression from the bulk of the postwar period [see Pagan and Schwert (1990) for evidence that the behavior of volatility was different during the Great Depression period]. Campbell (1991) uses the same break point and French, Schwert, and Stambaugh (1987) use a similar one. As a further check on robustness, we estimated monthly models over the period 1952–86, thereby excluding the stock market crash of October 1987. We do not report the 1952–86 results since they were generally similar to those for 1952–88, although parameters were less precisely estimated when we excluded the crash.
We estimate our model using numerical maximum likelihood. This procedure is subject to the same caveat that applies to all empirical work with GARCH-M models, namely that sufficient regularity conditions for consistency and asymptotic normality of the maximum likelihood estimator are not yet available. Recent work by Lumsdaine (1990) proves both consistency and asymptotic normality for a class of GARCH and integrated GARCH models, but these results cannot be directly extended to GARCH-M models. Below we treat our estimates as if they are indeed asymptotically normal.

In appendix B we derive the likelihood function for our model. Several complications arise from the quadratic relation between excess returns $h_{t+1}$ and dividend news $\eta_{d,t+1}$. First, the likelihood function needs to include a Jacobian term to account for the fact that the observed variable $h_{t+1}$ is a nonlinear function of the underlying conditionally normal variable $\eta_{d,t+1}$, where the functional relation depends on the unknown parameters of the model. Second, for certain parameter values the observed return may exceed the maximum that can be generated by our model. We handle this by imposing a prohibitive penalty on the likelihood for parameters which cause this problem. In practice this means that the estimated parameters cannot imply too much curvature; the maximum possible return must be larger than any observed return, so that the relevant part of the news-return relationship is upward-sloping, as it is in fig. 2. Third, for any observed return there are two possible realizations of $\eta_{d,t+1}$. We assume that the probability of the larger root, on the downward-sloping part of the news-return relationship, is zero, so that we always pick the smaller root. Strictly speaking, this means that our estimation procedure is only an approximation to maximum likelihood. However, our procedure is an extremely accurate approximation when the model has the moderate curvature we estimate from the data. After estimating the parameters, we can compute the implied probability at each point in the sample of a shock greater than the larger root. This probability never exceeds $10^{-7}$ in any of the models we estimate.

### 3.2 Basic Empirical Results

Tables 2a and 2b report maximum likelihood parameter estimates for monthly and daily data respectively. In each table the top panel gives results for the full
sample period 1926–88, the middle panel gives results for the first subsample 1926–51, and the bottom panel gives results for the second subsample 1952–88. Within each panel, the top row reports parameter estimates for the standard QGARCH-M model [eq. (12) with \( \lambda = 0 \) but nonzero \( \gamma \)]. The second row estimates our asymmetric QGARCH-M model with \( \lambda \) restricted as in eq. (11), and the third row estimates a more general model in which \( \lambda \) is a free parameter. Preliminary exploration of the data suggested that a QGARCH(1, 1) model is sufficient for monthly data, while a QGARCH(1, 2) model is required to capture the dynamics of the variance in daily data.\(^2\) Accordingly, table 2a reports a monthly QGARCH(1, 1) specification, while table 2b reports a daily QGARCH(1, 2).

In the daily QGARCH(1, 2) estimation we allowed the coefficient on the lagged error, \( \alpha_2 \), to be negative. Coefficients in GARCH models are often restricted to be nonnegative in order to guarantee that the variance \( \sigma_t^2 \) is positive; however, this restriction is stronger than necessary. In a QGARCH(1, 2) or GARCH(1, 2) model, \( \sigma_t^2 \) is positive if \( \omega, \alpha_1, \) and \( \beta \) are nonnegative and \(-\alpha_2 \leq \beta \alpha_1\). We find that allowing a negative \( \alpha_2 \) significantly improves the fit of the model without violating the positivity restriction on \( \sigma_t^2 \).

Most of our results are quite similar in monthly and daily data and in our different sample periods, but there are some anomalous results for monthly data in the period 1952–88. In this period the likelihood function is not well behaved; after extensive search in the parameter space we report the parameters that deliver the highest likelihood value, but very different parameters, similar to those reported for daily data and for other monthly sample periods, give almost as high a likelihood. We suspect that even with 444 postwar monthly observations there may be finite-sample problems with estimation in this period. For this reason we place greater emphasis on results obtained from daily data.

Our results can be summarized as follows. First, the estimates of the parameters that govern the dynamics of variance, \( \omega, \alpha \) (or \( \alpha_1 \) and \( \alpha_2 \)), and \( \beta \), are generally little affected by the changes in specification across rows of the tables. The sum \( \alpha + \beta \) (or \( \alpha_1 + \alpha_2 + \beta \)), which governs the persistence of the

\(^2\)At an early stage of our research, we tried to account for possible nontrading effects in daily returns by first removing a short moving average from returns and then estimating GARCH models on the transformed series. The results were very similar to GARCH results for the raw series.
Table 2a
Monthly estimates of the volatility feedback effect

<table>
<thead>
<tr>
<th>Model</th>
<th>$\omega \times 10^5$ (SE)</th>
<th>$\alpha \times 10^2$ (SE)</th>
<th>$\beta \times 10^2$ (SE)</th>
<th>$\mu \times 10^3$ (SE)</th>
<th>$\gamma$ (SE)</th>
<th>$\lambda$ (SE)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Sample period: January 1926 to December 1988; number of observations: 756</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>$\lambda = 0$</td>
<td>8.173 (0.015)</td>
<td>0.109 (0.684)</td>
<td>1.694 (0.024)</td>
<td>5.340 (2.597)</td>
<td>0.306 (1.024)</td>
<td>0.000 (1.024)</td>
</tr>
<tr>
<td>$\lambda$ restricted</td>
<td>7.870 (0.022)</td>
<td>0.120 (0.575)</td>
<td>1.694 (0.025)</td>
<td>5.366 (1.598)</td>
<td>0.316 (0.146)</td>
<td>0.789 (0.102)</td>
</tr>
<tr>
<td>$\lambda$ free</td>
<td>8.680 (0.022)</td>
<td>0.120 (0.557)</td>
<td>1.567 (0.025)</td>
<td>2.910 (2.695)</td>
<td>1.669 (1.203)</td>
<td>0.871 (0.131)</td>
</tr>
<tr>
<td>Sample period: January 1926 to December 1951; number of observations: 312</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>$\lambda = 0$</td>
<td>9.568 (0.032)</td>
<td>0.113 (1.747)</td>
<td>2.456 (0.032)</td>
<td>11.119 (4.225)</td>
<td>$-$0.478 (1.148)</td>
<td>0.000 (1.148)</td>
</tr>
<tr>
<td>$\lambda$ restricted</td>
<td>10.865 (0.022)</td>
<td>0.131 (1.270)</td>
<td>1.892 (0.035)</td>
<td>9.152 (2.953)</td>
<td>0.263 (0.177)</td>
<td>0.695 (0.166)</td>
</tr>
<tr>
<td>$\lambda$ free</td>
<td>10.960 (0.032)</td>
<td>0.132 (1.278)</td>
<td>1.878 (0.036)</td>
<td>8.956 (4.115)</td>
<td>0.344 (1.196)</td>
<td>0.670 (0.180)</td>
</tr>
<tr>
<td>Sample period: January 1952 to December 1988; number of observations: 444</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>$\lambda = 0$</td>
<td>54.389 (0.054)</td>
<td>0.137 (2.256)</td>
<td>8.071 (0.107)</td>
<td>12.219 (4.096)</td>
<td>$-$4.371 (2.512)</td>
<td>0.000 (2.512)</td>
</tr>
<tr>
<td>$\lambda$ restricted</td>
<td>8.581 (0.028)</td>
<td>0.072 (1.123)</td>
<td>3.480 (0.060)</td>
<td>9.152 (3.210)</td>
<td>0.263 (0.177)</td>
<td>1.982 (0.534)</td>
</tr>
<tr>
<td>$\lambda$ free</td>
<td>30.155 (0.047)</td>
<td>0.130 (1.364)</td>
<td>6.798 (0.113)</td>
<td>11.500 (3.988)</td>
<td>$-$5.980 (3.801)</td>
<td>1.675 (0.734)</td>
</tr>
</tbody>
</table>

Maximum likelihood parameter estimates for monthly CRSP value-weighted index returns in excess of one-month Treasury bill returns. All returns are measured in logarithms. The values in parentheses are asymptotic standard errors. The model for monthly excess returns, $h_{t+1}$, is

$$h_{t+1} = \mu + \gamma \sigma_t^2 + \kappa \eta_{t+1} - \lambda (\eta_{t+1}^2 - \sigma_t^2)$$

$$\sigma_t^2 = \omega + \alpha (\eta_{t+1} - b)^2 + \beta \sigma_{t-1}^2$$

$$\kappa = 1 + 2\lambda b,$$

where $\sigma_t^2$ is the conditional variance of $h_{t+1}$ and the parameter $\lambda$ measures the volatility feedback effect. The restricted model sets

$$\lambda = \frac{\gamma \rho \alpha}{1 - \rho (\alpha + \beta)}.$$
Maximum likelihood parameter estimates for daily Schwert (1990a) index returns spliced to daily CRSP value-weighted index returns. The returns are measured in excess of the monthly one-month Treasury bill return divided by the number of trading days in the month. All returns are measured in logarithms. The values in parentheses are asymptotic standard errors.

The model for daily excess returns, \( h_{t+1} \), is given by the qGARCH(1,2) analogues of eqs. (6), (11), and (12') in the text:

\[
h_{t+1} = \mu + \gamma \sigma_t^2 + \kappa \eta_{d,t+1} - \lambda (\eta_{d,t+1}^2 - \sigma_t^2),
\]

\[
\sigma_t^2 = \omega + \alpha_1 (\eta_{d,t} - b)^2 + \alpha_2 (\eta_{d,t-1} - b)^2 + \beta \sigma_{t-1}^2
\]

\[
\kappa = 1 + 2\lambda \beta,
\]

where \( \sigma_t^2 \) is the conditional variance of \( h_{t+1} \) and the parameter \( \lambda \) measures the volatility feedback effect. The restricted model sets

\[
\lambda = \frac{\gamma \rho (\alpha_1 + \rho \alpha_2)}{1 - \rho (\alpha_1 + \rho \alpha_2 + \beta)}
\]

is set equal to zero or is left unrestricted.

Our estimates imply that a volatility shock has a half-life between 12 and 18 months in monthly data over the full sample and the prewar subsample. In the

### Table 2B

Daily estimates of the volatility feedback effect

<table>
<thead>
<tr>
<th>Model</th>
<th>( \omega \times 10^7 ) (SE)</th>
<th>( \alpha_1 ) (SE)</th>
<th>( \alpha_2 ) (SE)</th>
<th>( b \times 10^3 ) (SE)</th>
<th>( \beta ) (SE)</th>
<th>( \mu \times 10^4 ) (SE)</th>
<th>( \gamma ) (SE)</th>
<th>( \lambda ) (SE)</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Sample period:</strong> January 2, 1926 to December 30, 1988; number of observations: 16,980</td>
<td></td>
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<td></td>
</tr>
<tr>
<td>( \lambda = 0 )</td>
<td>2.615 (0.809)</td>
<td>0.146 (0.009)</td>
<td>-0.078 (0.010)</td>
<td>2.604 (0.193)</td>
<td>0.926 (0.004)</td>
<td>3.531 (0.686)</td>
<td>0.223 (0.813)</td>
<td>0.000 (0.813)</td>
</tr>
<tr>
<td>( \lambda ) restricted</td>
<td>2.229 (0.762)</td>
<td>0.144 (0.009)</td>
<td>-0.076 (0.010)</td>
<td>2.626 (0.188)</td>
<td>0.926 (0.004)</td>
<td>3.596 (0.545)</td>
<td>0.094 (0.023)</td>
<td>1.090 (0.113)</td>
</tr>
<tr>
<td>( \lambda ) free</td>
<td>2.220 (0.780)</td>
<td>0.145 (0.009)</td>
<td>-0.076 (0.010)</td>
<td>2.624 (0.189)</td>
<td>0.926 (0.004)</td>
<td>3.588 (0.682)</td>
<td>0.116 (0.816)</td>
<td>1.089 (0.113)</td>
</tr>
<tr>
<td><strong>Sample period:</strong> January 2, 1926 to December 31, 1951; number of observations: 7,656</td>
<td></td>
<td></td>
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<td></td>
</tr>
<tr>
<td>( \lambda = 0 )</td>
<td>6.632 (2.167)</td>
<td>0.113 (0.009)</td>
<td>-0.022 (0.008)</td>
<td>4.509 (0.335)</td>
<td>0.893 (0.005)</td>
<td>3.876 (1.306)</td>
<td>-0.282 (0.979)</td>
<td>0.000 (1.901)</td>
</tr>
<tr>
<td>( \lambda ) restricted</td>
<td>5.780 (2.908)</td>
<td>0.114 (0.012)</td>
<td>-0.024 (0.013)</td>
<td>4.477 (0.435)</td>
<td>0.894 (0.008)</td>
<td>4.088 (1.013)</td>
<td>0.124 (0.036)</td>
<td>0.715 (0.163)</td>
</tr>
<tr>
<td>( \lambda ) free</td>
<td>5.926 (2.966)</td>
<td>0.114 (0.012)</td>
<td>-0.024 (0.013)</td>
<td>4.493 (0.437)</td>
<td>0.894 (0.008)</td>
<td>3.605 (1.277)</td>
<td>0.116 (0.096)</td>
<td>0.723 (0.163)</td>
</tr>
<tr>
<td><strong>Sample period:</strong> January 2, 1952 to December 30, 1988; number of observations: 9,324</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>( \lambda = 0 )</td>
<td>0.959 (0.744)</td>
<td>0.170 (0.013)</td>
<td>-0.117 (0.013)</td>
<td>2.431 (0.227)</td>
<td>0.941 (0.005)</td>
<td>3.734 (0.979)</td>
<td>-0.282 (1.901)</td>
<td>0.000 (1.901)</td>
</tr>
<tr>
<td>( \lambda ) restricted</td>
<td>0.768 (0.722)</td>
<td>0.156 (0.012)</td>
<td>-0.100 (0.013)</td>
<td>2.460 (0.216)</td>
<td>0.938 (0.005)</td>
<td>3.442 (0.640)</td>
<td>0.289 (0.077)</td>
<td>2.398 (0.284)</td>
</tr>
<tr>
<td>( \lambda ) free</td>
<td>0.792 (0.753)</td>
<td>0.156 (0.013)</td>
<td>-0.100 (0.013)</td>
<td>2.452 (0.218)</td>
<td>0.937 (0.005)</td>
<td>3.418 (0.978)</td>
<td>0.390 (1.977)</td>
<td>2.340 (0.282)</td>
</tr>
</tbody>
</table>
postwar monthly data, the implied half-life of a shock varies across specifications for the reasons given above: it is five months in the restricted $\lambda$ model, but less than one month in the other models. In daily data the half-life is about six months over the full sample, two months in the prewar subsample, and six months in the postwar subsample. These half-life estimates tend to be greater than those reported by Poterba and Summers (1986), which were just over two months for the full sample period and just over one month for the postwar period. The difference is probably due to Poterba and Summers’ use of an ARIMA model for a moving average of squared daily returns. Chou (1988), estimating a GARCH model on weekly data in the period 1962–85, found a volatility half-life of about one year.

Although there is some variation in the estimated persistence of volatility in different sample periods, the fitted values of volatility are similar for the whole period and the subperiods. Fig. 3 shows monthly averages of estimated daily values of $\sigma_t$. (We use daily data because we feel that the daily parameter estimates are more reliable than the monthly parameter estimates; we then average the daily standard deviations within each month to obtain a series that can be plotted.) The solid line is based on full sample estimates of our restricted $\lambda$ model, while the dashed line is based on subsample estimates of the same model. The two lines are always very close together.

Turning to the parameter $b$, which governs predictive asymmetry in the QGARCH model, we find that $b$ is always estimated to be positive. The estimates are significantly different from zero at the 5% level or better, except for monthly data in the prewar period. As one would expect from these estimates, likelihood ratio tests strongly reject the GARCH model in favor of the QGARCH model except in the prewar monthly data set. The QGARCH model appears to capture most of the predictive asymmetry in the data. A simple measure of predictive asymmetry is the correlation between today’s realization of a random variable $X_t$ and tomorrow’s squared realization $X_{t+1}^2$. When we calculate this correlation for normalized residuals of daily QGARCH and GARCH models, we find that it always lies between $-0.05$ and $-0.07$ for simple GARCH specifications, but is between $-0.01$ and $-0.02$ for QGARCH specifications. Allowing for volatility feedback has almost no effect on this measure of predictive asymmetry.
A third result is that the coefficient $\gamma$ is imprecisely estimated in the first and third rows of each panel. In these rows the only information on $\gamma$ comes from the changing conditional mean return. This is not sufficient to identify $\gamma$ well, given that our information set includes only the past history of returns. In the full sample our estimates of $\gamma$ are positive but insignificantly different from zero, while in the postwar period our $\gamma$ estimates are sometimes negative (but again insignificantly different from zero). Likelihood ratio tests do not reject a model imposing $\gamma = 0$ against the alternative of a free $\gamma$ with $\lambda = 0$. French, Schwert, and Stambaugh (1987) also found weak evidence against the hypothesis that $\gamma = 0$.

Fourth, the coefficient $\lambda$ is highly significant in the models in which it appears. In monthly data $\lambda$ is at least four standard errors from zero (except for the free $\lambda$ in postwar monthly data, which is only 2.3 standard errors from zero), and in daily data $\lambda$ is at least four and more commonly almost ten standard errors from zero. When $\lambda$ and $\gamma$ are linked together by the restriction (11), $\gamma$ becomes positive and is precisely estimated. In the postwar period, $\lambda$ tends to be larger than in the full sample or the prewar period.

Table 3 reports likelihood ratio tests of models that restrict $\lambda$ against more general alternatives. Again the results are quite similar for monthly and daily data. The data strongly reject models with $\lambda = 0$ against models with nonzero $\lambda$. The restriction relating $\lambda$ to the other parameters, by contrast, is rejected only in the anomalous monthly postwar data.

3.3 The Economic Importance of Volatility Feedback

We have shown that volatility feedback is statistically significant, but what is its economic significance? In this section we present several measures of the effect of volatility feedback on stock prices. We begin in fig. 4 by plotting the volatility discount implied by our model at each point in the sample. The volatility discount is defined as the log difference between the actual stock price and the price that would prevail in the absence of uncertainty about future dividends. It is given by the second two terms on the right-hand side of eq. (9). As in fig. 3, we use daily restricted $\lambda$ models to obtain daily volatility discounts; we then average these within each month before plotting. The solid line is based on
Table 3
Statistical significance of volatility feedback

<table>
<thead>
<tr>
<th>Sample period</th>
<th>$H_0: \lambda = 0$</th>
<th>$H_0: \lambda_{\text{restricted}}$</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Panel A: Likelihood ratio tests for monthly data</td>
<td></td>
<td></td>
</tr>
<tr>
<td>January 1926–December 1988</td>
<td>29.761</td>
<td>1.419</td>
</tr>
<tr>
<td>756 Observations</td>
<td>(0.000)</td>
<td>(0.234)</td>
</tr>
<tr>
<td>January 1926–December 1951</td>
<td>11.780</td>
<td>0.005</td>
</tr>
<tr>
<td>312 Observations</td>
<td>(0.001)</td>
<td>(0.945)</td>
</tr>
<tr>
<td>444 Observations</td>
<td>(0.001)</td>
<td>(0.001)</td>
</tr>
<tr>
<td>Panel B: Likelihood ratio tests for daily data</td>
<td></td>
<td></td>
</tr>
<tr>
<td>January 2, 1926–December 31, 1988</td>
<td>70.598</td>
<td>0.054</td>
</tr>
<tr>
<td>16,980 Observations</td>
<td>(0.000)</td>
<td>(0.816)</td>
</tr>
<tr>
<td>January 2, 1926–December 31, 1951</td>
<td>17.206</td>
<td>0.273</td>
</tr>
<tr>
<td>7,656 Observations</td>
<td>(0.000)</td>
<td>(0.601)</td>
</tr>
<tr>
<td>January 2, 1952–December 30, 1988</td>
<td>71.610</td>
<td>0.013</td>
</tr>
<tr>
<td>9,324 Observations</td>
<td>(0.000)</td>
<td>(0.912)</td>
</tr>
</tbody>
</table>

Likelihood ratio tests against the alternative of an unrestricted $\lambda$. The values in parentheses are the asymptotic $\chi^2$ probability values of the test statistics. The monthly data are monthly CRSP value weighted index returns in excess of one-month Treasury bill returns. The daily data use the daily Schwert (1990a) index returns spliced to the daily CRSP value-weighted index returns. The daily returns are measured in excess of the monthly return on a one-month Treasury bill divided by the number of trading days in the month. All returns are measured in logarithms.

The model for monthly excess returns, $h_{t+1}$, is

\[
\begin{align*}
    h_{t+1} &= \mu + \gamma \sigma_t^2 + \kappa \eta_{t,t+1} - \lambda (\eta_{t,t+1}^2 - \sigma_t^2) \\
    \sigma_t^2 &= \omega + \alpha (\eta_{d,t} - b)^2 + \beta \sigma_{t-1}^2 \\
    \kappa &= 1 + 2\lambda b.
\end{align*}
\]

where $\sigma_t^2$ is the conditional variance of $h_{t+1}$. The restricted model imposes

\[
\lambda = \frac{\gamma \rho \alpha}{1 - \rho (\alpha + \beta)}.
\]

The model for daily excess returns, $h_{t+1}$, is given by the QGARCH(1,2) analogues of eqs. (6), (11), and (12') in the text:

\[
\begin{align*}
    h_{t+1} &= \mu + \gamma \sigma_t^2 + \kappa \eta_{d,t+1} - \lambda (\eta_{d,t+1}^2 - \sigma_t^2) \\
    \sigma_t^2 &= \omega + \alpha_1 (\eta_{d,t} - b)^2 + \alpha_2 (\eta_{d,t-1} - b)^2 + \beta \sigma_{t-1}^2 \\
    \kappa &= 1 + 2\lambda b.
\end{align*}
\]

where $\sigma_t^2$ is the conditional variance of $h_{t+1}$. The restricted model imposes

\[
\lambda = \frac{\gamma \rho (\alpha_1 + \rho \alpha_2)}{1 - \rho (\alpha_1 + \rho \alpha_2 + \beta)}.
\]

full sample parameter estimates, while the dashed line uses subsample estimates.

The full sample estimates imply a volatility discount that is normally between
The volatility discount, given by the \texttt{qgarch}(1,2) analogue of the second and third terms on the right hand side of eq. (2.9) in the text, is

\[
\frac{\gamma}{1 - \rho} \left( \frac{\omega + (\alpha_1 + \alpha_2)h^2}{1 - (\alpha_1 + \alpha_2 + \beta)} \right) + \frac{\gamma}{1 - \rho(\alpha_1 + \alpha_2 + \beta)} \left( \sigma_t^2 - \frac{\omega + (\alpha_1 + \alpha_2)h^2}{1 - (\alpha_1 + \alpha_2 + \beta)} \right).
\]

The solid line uses full sample daily estimates of the restricted model (table 2b, top panel, row 2). The dashed line uses daily estimates over subsamples of the same model (table 2b, bottom two panels, row 2). The daily estimates are averaged within each calendar month. The model for daily excess returns is given by the \texttt{qgarch}(1,2) analogues of eqs. (6), (11) and (12') in the text:

\[
\begin{align*}
    h_{t+1} &= \mu + \gamma \sigma_t^2 + \kappa \eta_{d,t+1} - \lambda (\eta_{d,t+1} - \sigma_t^2) \\
    \sigma_t^2 &= \omega + \alpha_1 (\eta_{d,t} - b)^2 + \alpha_2 (\eta_{d,t-1} - b)^2 + \beta \sigma_{t-1}^2 \\
    \lambda &= \frac{\gamma \rho(\alpha_1 + \rho \alpha_2)}{1 - \rho(\alpha_1 + \rho \alpha_2 + \beta)} \\
    \kappa &= 1 + 2\lambda b,
\end{align*}
\]

where \(h_{t+1}\) is the daily log excess return and \(\sigma_t^2\) is the conditional variance of \(h_{t+1}\).

5% and 6%, rising above 10% in the early 1930’s and above 7% in October 1987. The subsample estimates imply a normal volatility discount of 10%, increasing to 12% in the early 1930’s and almost 14% in October 1987. (The 14% discount for that month averages daily discounts ranging from 10% to almost 25%, as we show in detail in fig. 6 below.)

The contribution of volatility feedback to the variance of returns varies
with the level of volatility, but it is generally very small, which is what one
would expect given the fairly stable volatility discounts shown in fig. 4. Eq. (15)
expresses the conditional variance of returns, divided by the conditional variance
of dividend news, as $\kappa^2 + 2\lambda^2 \sigma_t^2$. In our restricted $\lambda$ models, estimated on daily
data, $\kappa$ ranges from 1.005 in the full sample to 1.012 in the postwar sample, so
$\kappa^2$ is in the range 1.010 to 1.024. Thus the QGARCH effect increases the volatility
of returns by 1-2%. The term $2\lambda^2 \sigma_t^2$ is normally even smaller, less than 0.1% at
the median level of daily volatility although it reaches a maximum of just over
4% in October 1987. In monthly data the excess variance terms are somewhat
larger but still modest: over the full sample $\kappa$ is 1.027, $\kappa^2$ is 1.055, and $2\lambda^2 \sigma_t^2$
has a median of 0.2% and never exceeds 5%. These small numbers for excess
variance suggest that there is little difficulty with our assumption (7) that the
expected return on the market depends on the news variance rather than the
overall return variance. They also suggest that volatility feedback cannot explain
the findings of Campbell and Shiller (1988) and Campbell (1991) that returns
are considerably more variable than revisions of dividend forecasts.

Volatility feedback has a more important effect on the skewness of returns.
This is shown in fig. 5, which averages daily estimates in the same manner as
figs. 3 and 4. The median conditional skewness of returns is about $-0.05$ in full
sample estimates or $-0.09$ in postwar estimates, but skewness reaches $-0.28$ in
the early 1930’s and $-0.84$ in October 1987. Due to the within-month averaging,
fig. 5 does not reveal these extreme values but nonetheless shows the pattern
of variation over time. Conditional excess kurtosis (not shown in a figure) is
normally less than 0.1 in daily estimates, but it reaches 0.3 in the early 1930’s
and almost 1.0 in October 1987. These moments are generated by the mixture
of a normal and a $\chi^2(1)$ distribution given in eq. (13), where the weight on the
$\chi^2(1)$ is usually 1-2%, rising to 5% in the early 1930’s and 13% in October 1987.

These results give an interesting perspective on the debate between Pindyck
(1984) and Poterba and Summers (1986) over the importance of volatility feed-
back for stock market movements. According to our estimates, Poterba and
Summers are generally correct in that changing volatility has little effect on the
level of stock prices. But during periods of high volatility, the feedback effect
can become dramatically more important. Furthermore, the importance of the
conditional skewness is given by

\[
\text{Skew}(h_{t+1}) = -2\lambda \sigma_t \frac{3\kappa^2 + 4\lambda^2 \sigma_t^2}{(\kappa^2 + 2\lambda^2 \sigma_t^2)^{3/2}}.
\]

(16)

The solid line uses full sample daily estimates of the restricted model (table 2b, top panel, row 2). The dashed line uses daily estimates over subsamples of the same model (table 2b, bottom two panels, row 2). The daily estimates are averaged within each calendar month. The model for daily excess returns is given by the \text{qGARCH}(1,2) analogues of eqs. (6), (11), and (12') in the text:

\[
h_{t+1} = \mu + \gamma \sigma_t^2 + \kappa \eta_{d,t+1} - \lambda (\eta_{d,t+1} - \sigma_t^2)
\]

\[
\sigma_t^2 = \omega + \alpha_1 (\eta_{d,t} - b)^2 + \alpha_2 (\eta_{d,t-1} - b)^2 + \beta \sigma_{t-1}^2
\]

\[
\lambda = \frac{\gamma \rho (\alpha_1 + \rho \alpha_2)}{1 - \rho (\alpha_1 + \rho \alpha_2 + \beta)}
\]

\[
\kappa = 1 + 2\lambda \beta,
\]

where \(h_{t+1}\) is the daily log excess return and \(\sigma_t^2\) is the conditional variance of \(h_{t+1}\).

feedback effect is not limited by the low persistence of volatility. When we restrict \(\lambda\) to be the appropriate function of \(\rho, \gamma, \) and the variance parameters, our estimates of \(\gamma\) generally become small (less than 0.3 in daily models). Since the volatility discount is proportional to \(\gamma\), it would be possible to have a strong volatility feedback effect with reasonable levels of risk aversion.

The previous discussion has emphasized the behavior of stock returns over
long periods of time. However, we can also use the daily data to look more carefully at the behavior of the stock market around the stock market crash of October 1987. Volatility feedback is more important when volatility is high and so should have an important role to play in this period.

The conditional standard deviation of daily news, $\sigma_t$, hovered close to 1% during September 1987 and the first part of October but then rapidly rose to almost 7% on the day of the crash, October 16, 1987. The sudden increase in volatility was followed by a gradual decline back to 1.5% at the end of January 1988. (As noted by other authors, the decline in volatility after the crash was more rapid than normal; our estimates imply that the normal half-life of a volatility shock is about six months in postwar daily data.) For this period, as well as others, estimates of the conditional standard deviation based on the full sample differ very little from estimates of $\sigma_t$ using only postwar data.

The implied volatility discount for September 1, 1987 to January 31, 1988 is shown in fig. 6. Full sample estimates show the discount increasing from about 6% to a maximum of 13%, and then gradually declining. Postwar estimates show the discount increasing from 9% to a maximum of almost 25%. The difference is due to the fact that the coefficients $\gamma$ and $\lambda$ are larger in postwar data. These discounts are large enough to play an important auxiliary role in our understanding of the crash period. Although they did not cause the crash (large discounts are obtained only when large underlying news shocks occur), they help to explain the severity of the market decline.

### 3.4 Alternative Models of Volatility Feedback

In this section we discuss the robustness of our results to some alternative specifications. We show that although our model of volatility feedback has a considerably better fit than similar models without feedback, it cannot completely account for the observed average levels of negative skewness and leptokurtosis. However, explicit attempts to remedy this shortcoming without resorting to a purely statistical description—using a skewed and leptokurtic distribution for the news—do not significantly improve the model. We also show that the significance of volatility feedback is not merely an artifact of the manner in which our particular volatility process fits the predictive asymmetry of the data.
No News is Good News


The sample period for this figure is September 1, 1987 to January 29, 1988. The volatility discount, given by the \textsc{qgarch}(1,2) analogue of the second and third terms on the right hand side of eq. (2.9) in the text, is

\[
\frac{\gamma}{1 - \rho} \left( \frac{\omega + (\alpha_1 + \alpha_2)h^2}{1 - (\alpha_1 + \alpha_2 + \beta)} \right) + \frac{\gamma}{1 - \rho(\alpha_1 + \alpha_2 + \beta)} \left( \sigma_t^2 - \frac{\omega + (\alpha_1 + \alpha_2)h^2}{1 - (\alpha_1 + \alpha_2 + \beta)} \right).
\]

The solid line uses full sample daily estimates of the restricted model (table 2b, top panel, row 2). The dashed line uses daily estimates over the postwar subsample of the same model (table 2b, bottom panel, row 2). The model for daily excess returns is given by the \textsc{qgarch}(1,2) analogues of eqs. (6), (11), and (12') in the text:

\[
\begin{align*}
    h_{t+1} &= \mu + \gamma \sigma_t^2 + \kappa \eta_{d,t+1} - \lambda (\eta_{d,t+1}^2 - \sigma_t^2) \\
    \sigma_t^2 &= \omega + \alpha_1 (\eta_{d,t} - b)^2 + \alpha_2 (\eta_{d,t-1} - b)^2 + \beta \sigma_{t-1}^2 \\
    \lambda &= \gamma \rho(\alpha_1 + \rho \alpha_2) \\
    \kappa &= 1 + 2\lambda b,
\end{align*}
\]

where \(h_{t+1}\) is the daily log excess return and \(\sigma_t^2\) is the conditional variance of \(h_{t+1}\).

One measure of the adequacy of our model of volatility feedback is its ability to produce model residuals that have the standard normal distribution implied by the underlying theory. For each model we divide the residuals by their estimated standard deviations. We compute the mean, variance, skewness, and excess kurtosis of the normalized residuals for all of the estimated models.
If a particular model is well specified, then its normalized residuals should have
a standard normal distribution with zero mean, unit variance, and zero skewness
and excess kurtosis.

Almost all our estimated models have negative mean residuals, but none of
these means are significantly different from zero. For the monthly models, the
mean residuals range from a low of $-0.051$, with a standard error of 0.058, to
0.002, with a standard error of 0.048. The means of the daily residuals range
from $-0.013$, with a standard error of 0.011, to $-0.010$ with a standard error
of 0.008. French, Schwert, and Stambaugh (1987) note that a standard GARCH-
$M$ model produces residuals with a significantly negative mean, i.e. the model
overestimates the average stock return. They conjecture that a model allowing
for skewness might correct for this. In fact, the generalization to QGARCH is
critical in eliminating this problem. In the first version of this paper [Camp-
bell and Hentschel (1991)], in which we estimated simple GARCH models with
volatility feedback, we obtained significantly negative mean residuals that were
typically three or four times as large as those reported here. The addition of
volatility feedback alone clearly has little effect on the mean residuals of GARCH
and QGARCH models.

Although all of the models have sample residual variances which exceed
unity the deviations from one are always well within a single standard error.
The variances of the standardized monthly residuals range from 1.003 to 1.039,
while those of the standardized daily residuals are between 1.005 and 1.010.
The addition of volatility feedback has only small effects on the variances of the
normalized residuals.

Volatility feedback is much more important in eliminating negative skew-
ness and excess kurtosis from model residuals. The residuals from models with
volatility feedback have only about one-half the skewness of the residuals from
simple QGARCH models. For the full sample, the monthly model without volatil-
ity feedback ($\lambda = 0$) has normalized residuals with skewness of $-0.865$. When
we allow for the volatility feedback effect according to our model ($\lambda$ restricted),
skewness is reduced to $-0.439$. If the parameter $\lambda$ is freely estimated, skewness
falls to $-0.417$. Given our sample size, the standard error for the skewness of
$N(0,1)$ variates is 0.089. In the pre- and postwar subsamples, the results are
very similar except that in the postwar subsample skewness is lower for all three models.

The normalized residuals from the daily model exhibit very similar patterns. In the full sample the standard error for skewness is 0.019. The estimated skewness for the model without volatility feedback ($\lambda = 0$) is $-0.516$. The introduction of volatility feedback according to our model reduces skewness to $-0.356$ and freely estimating $\lambda$ does not reduce skewness further. Once again the results for the subsamples are very similar to those reported for the full sample.

Excess kurtosis is also greatly reduced in most sample periods. For the monthly full sample, the standard error for excess kurtosis is 0.178. The estimated excess kurtosis of the normalized residuals is 2.936 when we do not allow for volatility feedback. When volatility feedback is introduced the excess kurtosis falls to 1.681 and 1.509 for the restricted $\lambda$ and unrestricted $\lambda$ models, respectively. The reductions of excess kurtosis are very similar in the subsamples with the exception of the anomalous monthly postwar sample; in this period excess kurtosis is reduced from 1.354 for the model without volatility feedback to 0.703 when $\lambda$ is unrestricted. When we restrict the parameter $\lambda$, excess kurtosis actually increases to 1.730. However, given the standard error of 0.232 for the estimates of excess kurtosis with this sample size, the increase from 1.354 to 1.730 is insignificant.

The reductions of excess kurtosis for the daily models are somewhat smaller but nonetheless significant. In the full sample the standard error for excess kurtosis is 0.038. The introduction of volatility feedback according to either the restricted or free $\lambda$ models reduces estimated excess kurtosis from 4.398 to 3.816. In the prewar subsample the reduction is slightly less, from 2.824 to 2.789 and 2.779 for the restricted $\lambda$ and the free $\lambda$ models, respectively. However, in the postwar subsample the reduction is much more substantial, from 5.079 to 3.446 and 3.441, respectively.

The volatility feedback effect could account for more of the observed skewness and leptokurtosis if $\lambda$ and $\gamma$ were larger. The reason that we do not estimate larger values of $\lambda$ and $\gamma$ seems to be that the skewness and excess kurtosis of stock returns do not increase with volatility in the way required by our model. When we regress the third and fourth powers of standard $qGARCH$ model resid-
uals onto QGARCH variance estimates, our model predicts that we should find negative and positive coefficients respectively [eqs. (16) and (17)]. In fact, we tend to obtain the reverse sign pattern, although the coefficients are not generally significant. What this means is that our model cannot fully explain the average level of skewness and excess kurtosis without predicting exaggerated levels of skewness and excess kurtosis in periods of high volatility. With high values of \( \lambda \), our model would not be able to account for rebounds following large stock market crashes because the constraint on the maximum possible return would become binding.

To address this issue, we have tried to develop models in which volatility feedback does not become more important as volatility increases. In particular, we have applied our basic approach to other models of changing variance [Hentschel (1992)]. Models of volatility feedback are only tractable when long-horizon forecasts are linearly related to short-horizon forecasts of some volatility measure, and when the expected stock return is linear in this same measure. In the QGARCH model used in this paper, forecasts of conditional variance are linear in current information and the expected return must be linear in variance. Alternatively, one can use a model in which the conditional standard deviation of returns follows a GARCH-like process but in which the shocks are absolute values of returns rather than squared returns. This can be combined with the assumption that the expected return is linear in conditional standard deviation, as suggested by French, Schwert, and Stambaugh (1987), among others.\(^3\) When volatility feedback is incorporated into the model, one obtains a tent-shaped rather than a parabolic news-return relationship, implying that the conditional skewness and excess kurtosis of returns are constant rather than increasing in conditional standard deviation. Unfortunately, the nondifferentiability of the absolute value function means that the absolute value model has a discontinuous likelihood function once volatility feedback is incorporated which greatly complicates estimation and inference. Hentschel (1992) reports preliminary results for this model and finds that it does not fit the data substantially better than

\(^3\)Nelson (1991) has recently proposed a model in which the log conditional standard deviation follows a linear process. Unfortunately, one cannot introduce volatility feedback into Nelson’s model without making the unorthodox assumption that the expected return is linear in the log conditional standard deviation of returns.
the model studied in this paper.

We have also considered alternative models of predictive asymmetry. Our QGARCH model with volatility feedback fits the correlation between stock returns and future volatility in two different ways. First, the news process itself displays predictive asymmetry as shown by eq. (18) setting $\lambda = 0$. This predictive asymmetry is generated by a nonzero QGARCH parameter $b$, and it is more important when conditional volatility $\sigma^2_t$ is low than when it is high because the QGARCH model horizontally shifts the parabola relating shocks today to volatility tomorrow. (A given shift is more important when shocks cluster around zero than when shocks are widely dispersed.) Second, the volatility feedback effect contributes additional predictive asymmetry as shown by eq. (18) setting $b = 0$. This predictive asymmetry is more important when conditional volatility $\sigma^2_t$ is high than when it is low, because (as noted earlier) the variance of the variance of a GARCH or QGARCH process increases more than proportionally with the level of the variance of the process. Thus news about the variance becomes more important relative to underlying news when the variance is already high than when it is low.

These effects of volatility on predictive asymmetry are somewhat arbitrary and raise the possibility that our estimates of $\lambda$ are significant only because we have allowed no other means for the model to fit predictive asymmetry in high-volatility periods. Our daily estimates imply that at mean or lower levels of volatility the predictive asymmetry coming from volatility feedback is trivially small relative to the predictive asymmetry coming from QGARCH. At the mean daily standard deviation of 0.095, for example, the full-sample estimates imply a correlation between news and future volatility of $-0.364$, almost exactly the same as the correlation between returns and future volatility. At a standard deviation of 0.07, however, close to the maximum in the sample, the correlation between news and future volatility is $-0.053$ while the correlation between returns and future volatility is $-0.159$. Thus volatility feedback does add modestly to the ability of the model to fit predictive asymmetry at high levels of volatility.

In order to ensure that our estimates of $\lambda$ are not sensitive to the way in which our model relates volatility and predictive asymmetry, we have estimated a variant of the QGARCH model (suggested to us by Daniel Nelson) in which
the shift parameter $b$ applies to normalized news rather than raw news. In this model, eq. (6) is replaced by

$$\sigma_t^2 = \omega + \alpha \sigma_{t-1}^2 \left( \frac{Y_t}{\sigma_{t-1}} - b \right)^2 + \beta \sigma_{t-1}^2,$$

while the other equations of the model are unchanged. This makes the conditional correlation of news and future volatility constant. It leads to a return process of the form (12)', but with a time-varying coefficient $\kappa_t = 1 + 2\lambda b \sigma_t$ and with a more complicated relationship between $\lambda$ and the underlying parameters of the model:

$$\lambda = \gamma \rho \alpha / (1 - \rho(\alpha(1 + b^2) + \beta)).$$

We have estimated the QGARCH(1,1) form of this model on both monthly and daily data and obtain similar results to those reported in the paper, with strong evidence that $\lambda$ is nonzero but only weak evidence against the restriction relating $\lambda$ to the other parameters of the model. The only important change in the results is that the latter restriction is rejected in monthly data over the full sample, although not in monthly data in the postwar period. We note also that the time-variation in $\kappa_t$ in this model makes the variance of returns a less successful proxy for the variance of underlying news. Thus our assumption (7) that expected returns are linear in news variance is less appealing in the context of the model (19), which is one reason that we do not use it as our main specification.

The first version of this paper [Campbell and Hentschel (1991)] employed a standard symmetric GARCH process. There we also obtained very similar results for the magnitude and significance of volatility feedback. We conclude that volatility feedback estimates are not very sensitive to the specification of the variance process.

4 Conclusion

We have estimated a model of volatility feedback in stock returns using a QGARCH model of changing variance that has recently been proposed by Engle (1990) and Sentana (1991). Unlike the simple GARCH model, the QGARCH model fits the negative correlation between stock returns and future volatility of returns, and it produces residuals with means close to zero. We show that the model fits U.S. stock return data significantly better when it incorporates a volatility feedback
or “no news is good news” effect. Volatility feedback explains somewhat less than half the skewness and excess kurtosis of qGARCH model residuals, without introducing any new parameters specifically to fit these moments. Our estimates of volatility discounts on stock prices are generally fairly stable at around 10%, but they can increase dramatically during episodes of high volatility. During October 1987, for example, the volatility discount reached a maximum of almost 25%.

We conclude with one caveat about the interpretation of our results. Our formal model assumes that changing expected excess returns are driven by changing volatility. The remaining component of returns is treated as being driven by news about dividends (strictly speaking, dividends and real interest rates). However it is quite possible that the underlying shock which we write as \( \eta_{d,t+1} \) also contains innovations in required excess returns arising from some source other than changing volatility. The only way to distinguish this possibility from the dividend news interpretation of \( \eta_{d,t+1} \) is by testing for the constancy of the volatility-adjusted conditional mean excess stock return for which the methods of this paper are not well suited. Earlier work reported in Campbell and Shiller (1988) and Campbell (1991) finds that changing expected stock returns are an important source of variation in unexpected stock returns, but in this paper we find that volatility feedback contributes little to the unconditional variance of returns. We therefore believe that much of the variance of \( \eta_{d,t+1} \) is in fact due to other changes in expected excess returns, and not to news about future dividends.

References


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Appendix A: The QGARCH(p, q) Model

The text discusses the case of QGARCH(1,1) in considerable detail. Here we extend the model to accommodate more general QGARCH(p,q) processes. Still more general forms of QGARCH, which allow for interactions of lagged shocks, are discussed in Sentana (1991); these can be handled by a straightforward extension of our approach.

For a QGARCH(p,q) process the variance is described by

$$\sigma_t^2 = \omega + \sum_{i=1}^{q} \alpha_i (\eta_{d,t+1-i} - b_i)^2 + \sum_{j=1}^{p} \beta_j \sigma_{t-j}^2.$$  (A.1)

Some algebraic manipulations allow us to solve (A.1) for $\eta_{d,t+1}^2$ in the following form:

$$\eta_{d,t+1}^2 = \omega' + \sum_{i=1}^{\max\{p,q\}} (\alpha_i + \beta_i) \eta_{d,t+1-i}^2 - 2 \sum_{i=1}^{q} \alpha_i b_i \eta_{d,t+1-i} + (\eta_{d,t+1}^2 - \sigma_t^2) - \sum_{j=1}^{p} \beta_j (\eta_{d,t+1-j}^2 - \sigma_{t-j}^2),$$  (A.2)

where $\beta_j = 0$ for $j > p$, $\alpha_i = 0$ for $i > q$, and $\omega' = \omega + \sum_{i=1}^{q} \alpha_i b_i^2$.

For canonical GARCH processes $b_i = 0$ and eq. (A.2) is an ARMA(max{p,q}, p) process for $\eta_{d,t+1}^2$ with mean zero innovations ($\eta_{d,t+1-j}^2 - \sigma_{t-j}^2$):

$$\eta_{d,t+1}^2 = \omega' + \sum_{i=1}^{\max\{p,q\}} \phi_i \eta_{d,t+1-i}^2 + \epsilon_{t+1} + \sum_{j=1}^{p} \theta_j \epsilon_{t+1-j},$$  (A.3)

where $\phi_i = (\alpha_i + \beta_i)$ and $\theta_j = -\beta_j$. In this ARMA case we can apply well-known results for the discounted sum of revisions in the expected future values of ARMA processes [Flavin (1981), Hansen and Sargent (1981)] to find $\eta_{h,t+1}$.

Unfortunately, when $b_i \neq 0$ there are additional terms of the form $-2\alpha_i b_i \eta_{h,t+1-i}$ preventing an ARMA representation. Nonetheless, we can find a state space representation for $\eta_{d,t+1}^2$, such that $\eta_{d,t+1}^2$ is the first element in the state vector $Z_{t+1}$ which follows the transition equation

$$Z_{t+1} = \omega' e_1 + T Z_t + RU_{t+1},$$  (A.4)
No News is Good News

\[ T = \begin{bmatrix}
\phi_1 & I_{m-1} & -2\alpha_1 b_1 & \ldots & -2\alpha_p b_p \\
\vdots & & \ddots & & \vdots \\
\phi_{m-1} & & & \ddots & \vdots \\
\phi_m & 0 & \ldots & 0 & 0 \\
0 & 0 & \ldots & 0 & 0 \\
0 & 0 & \ldots & 0 & 0 \\
\vdots & 0 & \ddots & \vdots & \vdots \\
0 & 0 & \ldots & 0 & 0 \\
0 & 0 & \ldots & 0 & 0 \\
\end{bmatrix}, \]

\[ R = \begin{pmatrix}
1 & 0 \\
\theta_1 & 0 \\
\vdots & \vdots \\
\theta_{m-1} & 0 \\
0 & 1 \\
0 & 0 \\
\vdots & \vdots \\
0 & 0 \\
\end{pmatrix}, \quad U_{t+1} = \begin{pmatrix}
\eta_{d,t+1}^2 \\
\eta_{d,t+1}^2 \\
\sigma_t^2 \\
\end{pmatrix}, \]

and \( e_1 = (1, 0, \ldots, 0)' \). The error term \( U_t \) has zero mean and is serially uncorrelated. Eq. (A.4) can be used to form the expectation of \( h_{t+1+j} \) for any horizon since \( E_t U_{t+1} = 0 \).

\[ E_{t+1} h_{t+1+j} = \mu + \gamma E_{t+1} \eta_{d,t+1+j}^2 \\
= \mu' + \gamma e_1' T^j Z_{t+1}, \quad (A.5) \]

The innovations in the expectations of \( h_{t+1+j} \) are given by

\[ (E_{t+1} - E_t) h_{t+1+j} = \gamma e_1' T^j (Z_{t+1} - T Z_t) \\
= \gamma e_1' T^j R U_{t+1}, \quad (A.6) \]

which says that the innovations in expectations for the QGARCH model of eq. (A.1) are in general a linear combination of \( \eta_{d,t+1} \) and \( (\eta_{d,t+1}^2 - \sigma_t^2) \).
Finally, we can solve the discounted sum of the innovations in expectations as

$$\eta_{h,t+1} = \sum_{j=1}^{\infty} \rho^j (E_{t+1} - E_t) h_{t+1+j}$$

$$= \gamma e_1' \sum_{j=1}^{\infty} \rho^j T^j RU_{t+1}$$

$$= \gamma p e_1' T(I - \rho T)^{-1} RU_{t+1}. \quad (A.7)$$

The sparsity of $T$ means that moderate order QGARCH models permit analytical solutions of eq. (A.7) in terms of the basic parameters. When eq. (A.7) is applied to the case of QGARCH$(1,2)$ we find that

$$\eta_{h,t+1} = -2 \frac{\gamma \rho (\alpha_1 b_1 + \rho \alpha_2 b_2)}{1 - \rho (\alpha_1 + \rho \alpha_2 + \beta)} \eta_{d,t+1} + \lambda (\eta_{d,t+1}^2 - \sigma_t^2) \quad (A.8)$$

and

$$\lambda = \frac{\gamma \rho (\alpha_1 + \rho \alpha_2)}{1 - \rho (\alpha_1 + \rho \alpha_2 + \beta)}. \quad (A.9)$$

When $b_1 = b_2 = b$, as we assume in the model of the text, this simplifies to

$$\eta_{h,t+1} = -2 \lambda b \eta_{d,t+1} + \lambda (\eta_{d,t+1}^2 - \sigma_t^2), \text{ similar to the QGARCH}(1,1) \text{ case but, of course, with a slightly different \( \lambda \). Under these restrictions on } b, \text{ the coefficient } \kappa \text{ on } \eta_{d,t+1} \text{ in eq. (12) can be written as } \kappa = 1 + 2 \lambda b. \text{ In the event that } \alpha_2 = 0, \text{ all terms of the form } \alpha_2 b_2 \text{ vanish and the solution reduces to the QGARCH}(1,1) \text{ case described in the text.}$$

Appendix B: Maximum Likelihood Estimation

The standard GARCH-M model is linear in the conditionally Gaussian error term, $\eta_{t+1}$, and the likelihood function is easily derived as the product of the conditional densities. Equivalently, the log likelihood function is given by the sum of the logarithms of the conditional densities.

In the extension of the GARCH-M framework discussed in this paper returns are a quadratic function of $\eta_{h,t+1}$. This stems not from the use of the quadratic

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For notational simplicity the $d$ subscript on $\eta_{d,t+1}$ is dropped in this appendix. Since $\eta_{h,t+1}$ is never mentioned, this should not lead to confusion.
garch model but from the presence of the term \( \lambda(\eta^2_{t+1} - \sigma^2_t) \) in eq. (12). Due to this quadratic relation the derivation of the likelihood function requires the use of some basic results for the transformation of random variables.

Recall that for a one-to-one transformation \( y = g(x) \) the distribution of \( y \), \( f_y(y) \), is given by

\[
f_y(y) = \left| \frac{dy}{dx} \right| f_x(g^{-1}(y)) \quad (B.1)
\]

where \( f_x(x) \) is the distribution of \( x \). Furthermore, if the transformation is not one-to-one, so that there are multiple roots \( g^{-1}_i(y) \), we can find the density of the transformed random variable by summing over all regions for which the transformation is one-to-one. Thus

\[
f_y(y) = \sum_i \left| \frac{dy}{dx} g^{-1}_i(y) \right| f_x(g^{-1}_i(y)), \quad (B.2)
\]

where \( g^{-1}_i(y) \) are the roots of the transformation.

In our model the observed variable \( y \) is the stock return \( h_{t+1} \), and the underlying variable is the news \( \eta_{t+1} \). The transformation \( g \) is

\[
h_{t+1} = g(\eta_{t+1}) = -\lambda \eta^2_{t+1} + \kappa \eta_{t+1} + \mu + (\gamma + \lambda) \sigma^2_t. \quad (B.3)
\]

As shown in fig. 2, this has the form of an inverted parabola, with two roots. The smaller root is associated with a positive slope.

When (B.2) is applied to (B.3) we find that

\[
f_h(h_{t+1}) = \left( \kappa^2 - 4\lambda [h_{t+1} - \mu - (\gamma + \lambda) \sigma^2_t] \right)^{-\frac{1}{2}} \times
\]

\[
\left( f_\eta(g^{-1}_1(h_{t+1})) + f_\eta(g^{-1}_2(h_{t+1})) \right), \quad (B.4)
\]

where

\[
g^{-1}_i(h_{t+1}) = \frac{\kappa - \sqrt{\kappa^2 - 4\lambda [h_{t+1} - \mu - (\gamma + \lambda) \sigma^2_t]}}{2\lambda}
\]

and
Maximum Likelihood Estimation

\[ g^{-1}_2(h_{t+1}) = \frac{\kappa + \sqrt{\kappa^2 - 4\lambda [h_{t+1} - \mu - (\gamma + \lambda)\sigma^2_t]}}{2\lambda}. \]  \hspace{1cm} (B.5)

We assume that observed returns always have a positive derivative with respect to the underlying shocks which generate them. In other words, the shocks occur in the range for which the inverted parabola in fig. 2 is upward sloping. Consequently, we always pick the smaller of the two roots above, \( \hat{\eta}_{t+1} = g^{-1}_1(h_{t+1}) \), which amounts to assuming \( f_\eta(g^{-1}_2(h_{t+1})) = 0 \). Since \( dy/dx = (dx/dy)^{-1} \) we can write the conditional density of \( h_{t+1} \) as

\[ f_h(h_{t+1}) = (\kappa - 2\lambda \hat{\eta}_{t+1})^{-1} f_\eta(\hat{\eta}_{t+1}). \]  \hspace{1cm} (B.6)

Finally we can write the conditional log likelihood function of \( h_{t+1} \) as a function of the conditionally normal errors \( \hat{\eta}_{t+1} \) as

\[ L(h_{t+1}) = -\log(\kappa - 2\lambda \hat{\eta}_{t+1}) - \frac{1}{2} \log(2\pi) - \frac{1}{2} \log(\sigma^2_t) - \frac{1}{2} \frac{\hat{\eta}^2_{t+1}}{\sigma^2_t}. \]  \hspace{1cm} (B.7)

This is the log likelihood function of the standard GARCH model for the implied shock \( \hat{\eta}_{t+1} \), plus an additional term arising from the Jacobian of the quadratic transformation.

Note that the likelihood function reduces to the standard GARCH-M case when \( \lambda \), the coefficient on the quadratic term, is zero.

When the roots \( g^{-1}_1(h_{t+1}) \) and \( g^{-1}_2(h_{t+1}) \) are real and distinct, \( \kappa - 2\lambda \hat{\eta}_{t+1} > 0 \) and the likelihood is well defined. The cases of identical or complex roots correspond to a situation in which an observed return equals or exceeds the maximum return which can be produced by the model. This situation is ruled out by penalizing the log likelihood function whenever the current parameter values imply \( \kappa - 2\lambda \hat{\eta}_{t+1} \leq 0 \).

After estimating the parameters of the model, we can check the accuracy of the approximation that \( f_\eta(g^{-1}_2(h_{t+1})) = 0 \) by calculating at each point in the sample the probability of a shock larger than \( g^{-1}_2(h_{t+1}) \), conditional on the model parameters and our current estimate of the state variable \( \sigma^2_t \). When we do this we find that the probability never exceeds \( 10^{-7} \), so there should be only trivial error introduced by our approximate method.